



in the orthogonal decomposition

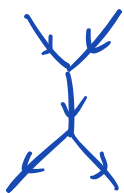
$$V_{l_1} \otimes V_{l_2} = \bigoplus_{|l_1 - l_2| \leq l_{12} \leq l_1 + l_2} V_{l_{12}}$$

In other words such vertex is a basis element in $\text{Hom}(V_{l_{12}}, V_{l_1} \otimes V_{l_2})$.

Vertex with the opposite orientation represents a basis in $\text{Hom}(V_{l_1} \otimes V_{l_2}, V_{l_{12}})$, i.e. a projection



We choose this basis such that



is an orthonormal projector, i.e.

$$\begin{array}{c}
 e \\
 \downarrow \\
 \circ \\
 \swarrow \quad \searrow \\
 l_1 \quad l_2 \\
 \downarrow \\
 e'
 \end{array}
 = \delta_{ee'} \downarrow e$$

Using this property we obtain for the q -6j symbol:

$$\begin{array}{c} \downarrow l_{123} \\ \text{---} l_1 \text{---} \\ \diagup l_{13} \diagdown \\ \text{---} l_2 \text{---} \\ \downarrow l_{12} \\ \downarrow l_{123} \end{array} \begin{array}{c} l_3 \\ \downarrow l_{23} \end{array} = \left\{ \begin{array}{c} l_1 \ l_2 \ l_{12} \\ l_3 \ l_{123} \ l_{23} \end{array} \right\} \downarrow l_{123}$$

or

$$\left\{ \begin{array}{c} l_1 \ l_2 \ l_{12} \\ l_3 \ l_{123} \ l_{23} \end{array} \right\} = \frac{1}{[2l+1]_{123}} \begin{array}{c} \downarrow l_{123} \\ \text{---} l_1 \text{---} \\ \diagup l_{13} \diagdown \\ \text{---} l_2 \text{---} \\ \downarrow l_{12} \\ \downarrow l_{123} \end{array}$$

Here we used the formula for the quantum dimension of V_l :

$$[2l+1] = \begin{array}{c} \curvearrowright \end{array} = \begin{array}{c} \curvearrowright \end{array} = [2l+1] \begin{array}{c} \curvearrowright \\ \cdot \\ \cdot \end{array}$$

Here $\begin{array}{c} \curvearrowright \\ \cdot \\ \cdot \end{array}$ is the projection to 1-dimensional representation $V_l \otimes V_l \rightarrow \mathbb{C}$ and $\begin{array}{c} \curvearrowleft \\ \cdot \\ \cdot \end{array}$ is the embedding $\mathbb{C} \subset V_l \otimes V_l$.

Note that

$$\begin{aligned}
 & \text{Diagram 1} = \text{Diagram 2}, & \begin{array}{l} \uparrow \downarrow \sim \varphi: V_e^* \rightarrow V_e \\ \downarrow \uparrow \sim \varphi^{-1}: V_e \rightarrow V_e^* \end{array} \\
 & = \text{Diagram 3} = \text{Diagram 4}
 \end{aligned}$$

and also

$$\text{Diagram 5} = \frac{1}{\sqrt{[2e+1]}} \text{Diagram 6}$$

$$\text{Diagram 7} = \frac{1}{\sqrt{[2e+1]}} \text{Diagram 8}$$

Recall some identities for 3j-symbols

(a)

$$\text{Diagram 9} = \text{Diagram 10}$$

$$(b) \quad \begin{array}{c} l_1 \quad l_2 \\ \swarrow \quad \searrow \\ \curvearrowright \\ \downarrow l \end{array} = (-1)^{l_1+l_2-l} q^{\frac{1}{2}(c_l - c_{l_1} - c_{l_2})} \begin{array}{c} l_1 \quad l_2 \\ \swarrow \quad \searrow \\ \downarrow l \end{array}$$

$$(c) \quad \begin{array}{c} l_1 \quad l_2 \\ \swarrow \quad \searrow \\ \downarrow l \end{array} = (-1)^{l+l_1-l_2} \left(\frac{[2l+1]}{[2l_2+1]} \right)^{\frac{1}{2}} \begin{array}{c} \downarrow \quad \downarrow \\ \curvearrowright \end{array}$$

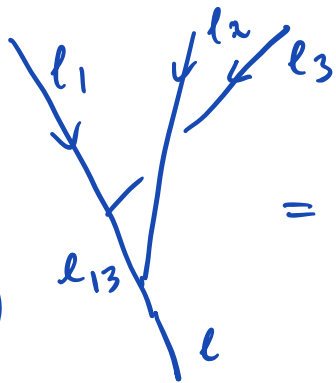
Corollary of (b):

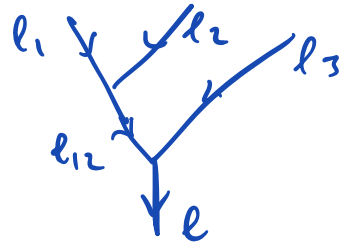
$$\begin{array}{c} \downarrow \quad \downarrow \\ \curvearrowright \end{array} = (-1)^{2l} q^{-c_l} \begin{array}{c} \downarrow \\ \downarrow \end{array}$$

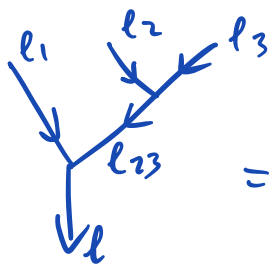
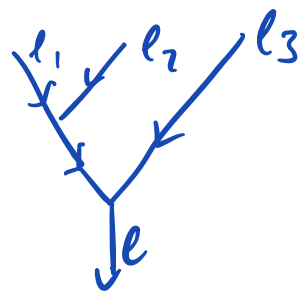
Now let us return to q -6j symbols.
Orthogonality of 3j symbols implies:

$$(d) \quad \begin{array}{c} l_1 \quad l_2 \quad l_{23} \\ \swarrow \quad \searrow \quad \nearrow \\ \downarrow l_{12} \quad \downarrow l_3 \\ \downarrow l_{123} \end{array} = \left. \begin{array}{c} l_1 \quad l_2 \quad l_{12} \\ l_3 \quad l_{123} \quad l_{23} \end{array} \right\} \begin{array}{c} l_1 \quad l_{23} \\ \swarrow \quad \searrow \\ \downarrow l_{123} \end{array}$$

Thm (*)

1)  = $\sum_{l_{12}} (-1)^{l_{12} + l_{13} - l - l_1} \frac{1}{2} (c_l + c_{l_1} - c_{l_{13}} - c_{l_{12}})$



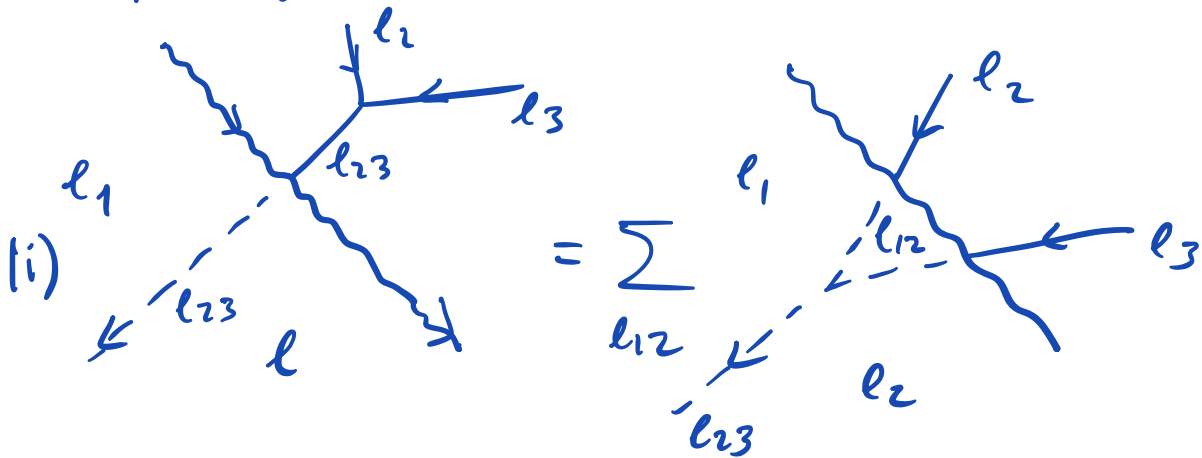
2)  = $\sum_{l_{12}} \left\{ \begin{matrix} l_3 & l_2 & l_{13} \\ l_1 & l & l_{12} \end{matrix} \right\}$ 

Proof (h/w)

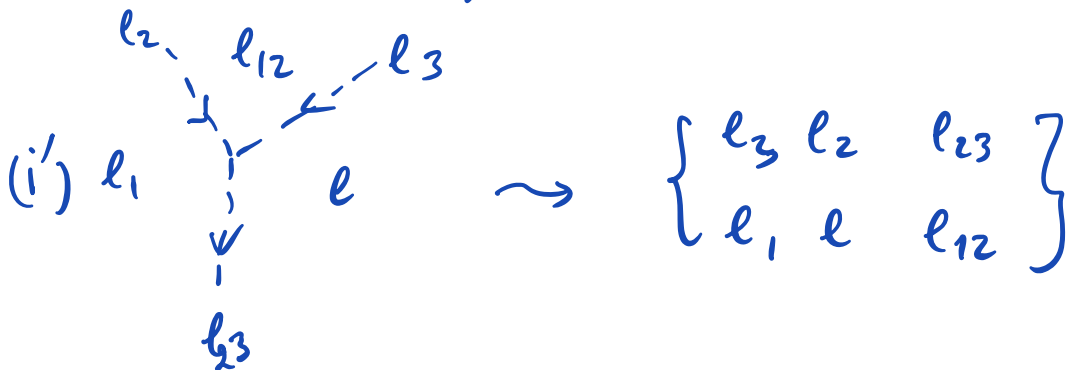
Corollary. Orthogonality of $q-6j$ symbols:

Shadow world for q - 6_j symbols

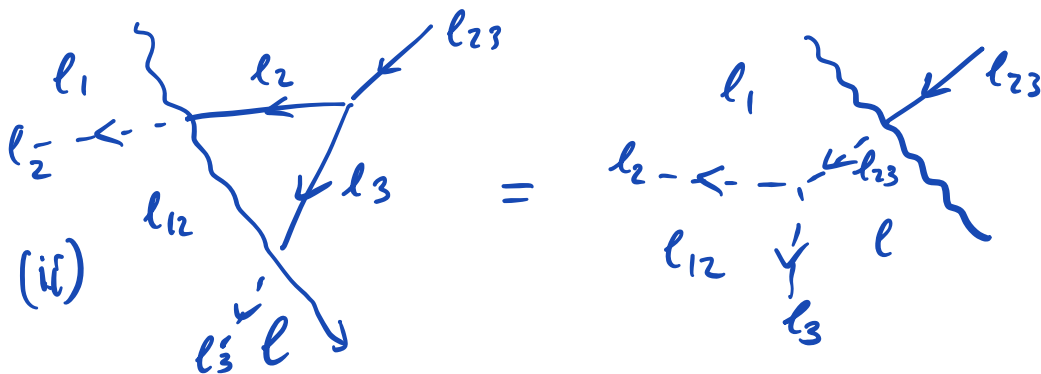
Write 2) from Thm (*) as the equality of diagrams



where we assign

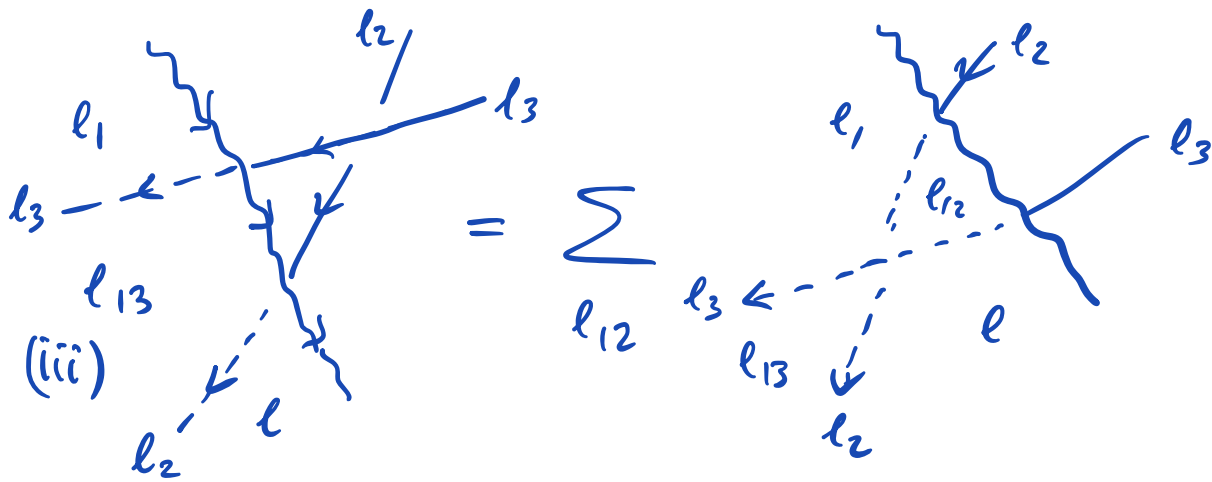


Similarly, the identity (2) can be written as

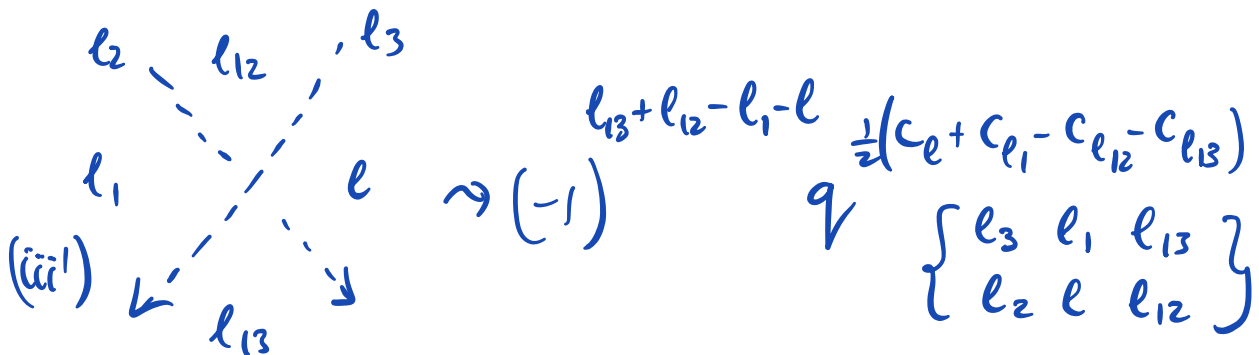




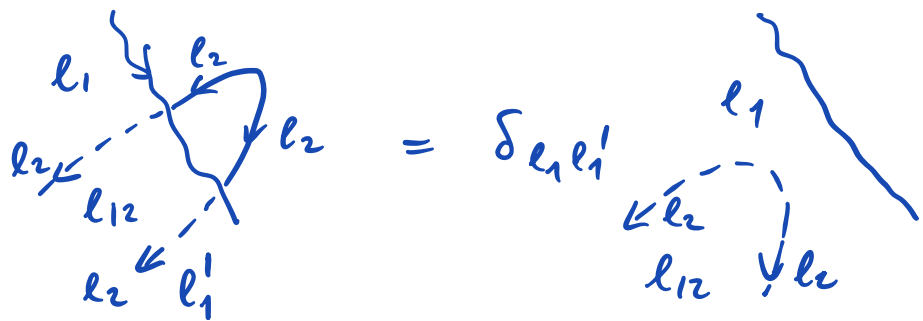
The identity (1) in Thm (*) can be written as



where



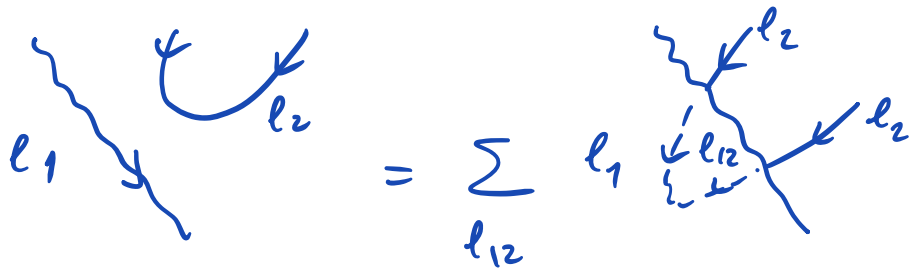
A particular case of (ii):



$$\begin{array}{c} l_2 \\ \swarrow \\ l_{12} \\ \searrow \\ l_1 \end{array} \begin{array}{c} l_1 \\ \swarrow \\ l_{12} \\ \searrow \\ l_2 \end{array} \rightsquigarrow (-1)^{l_1+l_2-l_{12}} \left(\frac{[2l_{12}+1]}{[2l_1+1]} \right)^{1/2} \delta(l_1, l_2, l_3)$$

Clebsch-Gordan rules: $|l_1 - l_2| \leq l_{12} \leq l_1 + l_2$

Similarly, a particular case of (i):



$$\begin{array}{c} l_1 \\ \swarrow \\ l_{12} \\ \searrow \\ l_1 \end{array} \begin{array}{c} l_2 \\ \swarrow \\ l_{12} \\ \searrow \\ l_2 \end{array} \rightsquigarrow (-1)^{l_1+l_2-l_{12}} \left(\frac{[2l_{12}+1]}{[2l_1+1]} \right)^{1/2} \delta(l_1, l_2, l_3)$$

This gives new formulae for invariants of knots and framed graphs obtained earlier.

(to be edited)